# Supporting Information 

# Light- and Magnetic-Responsive Synergy Controlled Reconfiguration of Polymer Nanocomposites with Shape Memory Assisted Self-Healing <br> Performance for Soft Robotics 

Yi Chen, Xing Zhao, Yan Li, Zhao-Yuan Jin, Yi Yang, Ming-Bo Yang, Bo Yin*

College of Polymer Science and Engineering, State Key Laboratory of Polymer Materials

Engineering, Sichuan University, Chengdu, 610065, Sichuan, People's Republic of China
*Corresponding author. Tel: $+86-28-85405324$; Fax: $+86-28-85405324$

E-mail address: yinbo@scu.edu.cn

## Supplementary Figures:



[^0]

Figure S2. The details of evolution of strain, stress, and temperature during the thermomechanical cycle of PCL/TPU blend.


Figure S3. (a) (b) SEM images of $\mathrm{PCL} / \mathrm{TPU} / \mathrm{Fe}_{3} \mathrm{O}_{4}$ nanocomposite for fracture morphology.


Figure S4. The snapshots of light-and magnetic- responsive controlled reconfiguration.


Figure S5. Measurement of bending angle of the nanocomposite film (length of the bending curved arc is 8 mm ).


Figure S6 The stress-strain curves of original, damaged and $1 \& 3$ healing cycles specimens.

## Supplementary Table:

Table.S1 Data of bending angle and the relevant parameter of curvature

| Magnetic-response |  |  | Light-response |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathrm{t} / \mathrm{s}$ | angle/ ${ }^{\circ}$ | curvature | $\mathrm{t} / \mathrm{s}$ | angle/ ${ }^{\circ}$ | curvature |
| 0 | 0 | 0 | 0 | 90 | 11.25 |
| 0.1 | 5 | 0.625 | 0.5 | 88 | 11 |
| 0.2 | 11 | 1.375 | 1 | 86 | 10.75 |
| 0.3 | 20 | 2.5 | 1.5 | 83 | 10.375 |
| 0.4 | 34 | 4.25 | 2 | 78 | 9.75 |
| 0.5 | 50 | 3.75 | 2.5 | 72 | 9 |
| 0.6 | 63 | 7.785 | 3 | 64 | 8 |
| 0.7 | 75 | 9.375 | 3.5 | 52 | 6.5 |
| 0.8 | 83 | 10.375 | 4 | 35 | 4.375 |
| 0.9 | 88 | 11 | 4.5 | 18 | 2.25 |
| 1.0 | 90 | 11.25 | 5 | 0 | 0 |

The calculation process of curvature is shown as follows:

$$
\text { curvature }=\frac{\Delta \alpha}{\Delta s}
$$

where $\Delta \alpha$ is bending angle. In actual engineering design problems, a section of arc adjacent to the bending point is often used to approximate the curved arc to simplify the problem. Therefore, the $\Delta \mathrm{s}$ is length of bending arc, and the approximate value is 8 mm here.

## Supplementary Videos:

Video. S1 Light-responsive shape recovery progress of the $\mathrm{PCL} / \mathrm{TPU} / \mathrm{Fe}_{3} \mathrm{O}_{4} @ \mathrm{PDA}$ nanocomposite.

Video. S2 Light- and magnitic-responsive synergy controlled reconfiguration and reversible shape transformation progress of the $\mathrm{PCL} / \mathrm{TPU} / \mathrm{Fe}_{3} \mathrm{O}_{4} @ \mathrm{PDA}$ nanocomposite in a cantilever experiment.


[^0]:    Figure S 1 . Schematic diagrams of the fabrication process for $\mathrm{PCL} / \mathrm{TPU} / \mathrm{Fe}_{3} \mathrm{O}_{4} @ \mathrm{PDA}$ nanocomposites

