

Supporting Information for

Highly Sensitive Mechano-Optical Strain Sensor Based on 2D Material for Human Gaits Quality Monitoring and High End Robotic Applications

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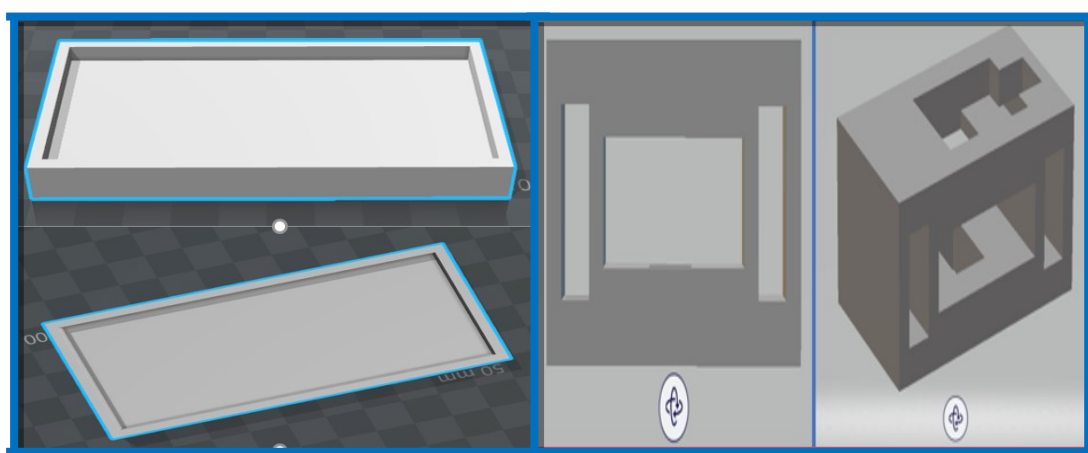


Fig. S1 (a) Design of casing for molding and casting of composite film **(b)** Design of LED-LDR assembly package.

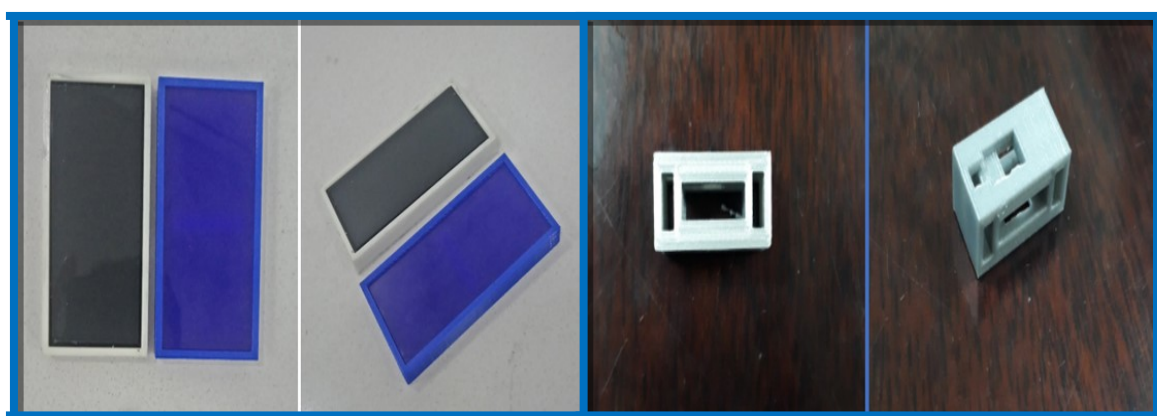


Fig. S2 Real-time images showing the: **(a)** 3D printing of casing for molding and casting of Ecoflex/MoS₂ composite film **(b)** 3D design of LED-LDR assembly package.

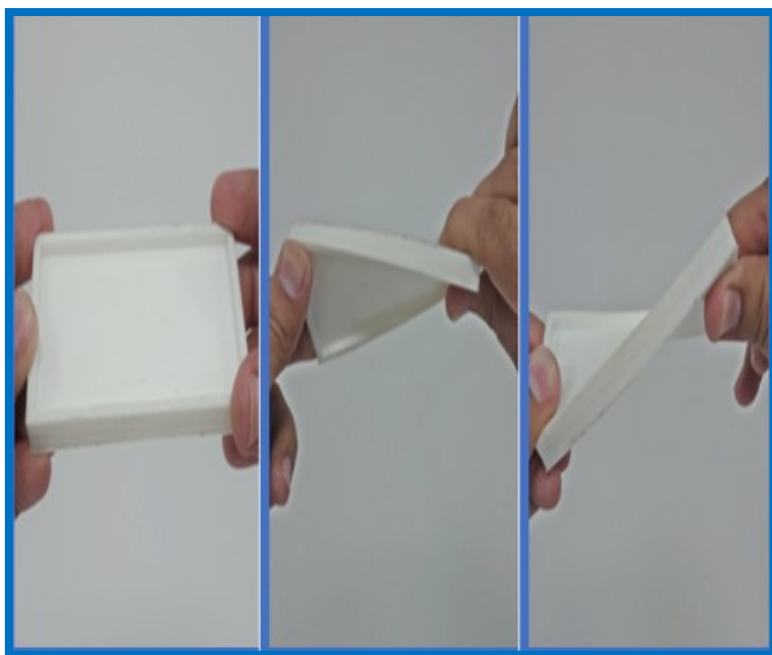


Fig. S3 Real-time images showing the flexibility of 3D printed casing for molding and casting of Ecoflex/MoS₂ composite film.



Fig. S4 Real-time images showing the casting of Ecoflex/MoS₂ composite film.

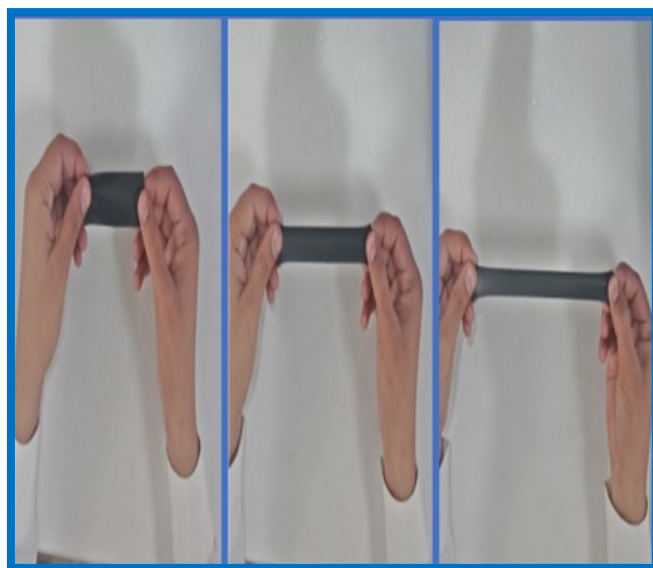


Fig. S5 Real-time images showing the manual stretching capability of Ecoflex/MoS₂ composite film.

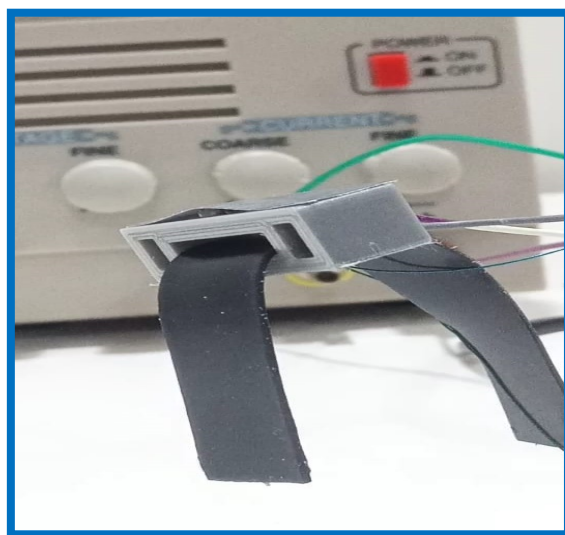


Fig. S6 Real-time images depicting the fabrication of a single sensor package based on Ecoflex/MoS₂ composite film and LED-LDR arrangements.

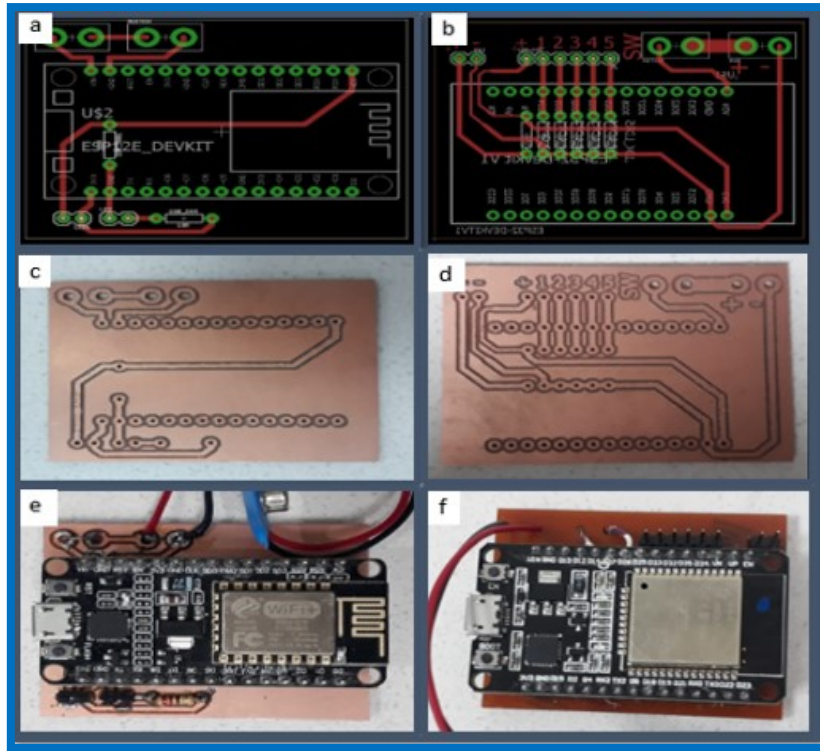


Fig. S7 (a, b) PCB design of hardware circuitry, **(c, d)** Printed PCB boards, and **(e, f)** real-time images of complete hardware circuitry for the acquisition of sensor data and remote monitoring.

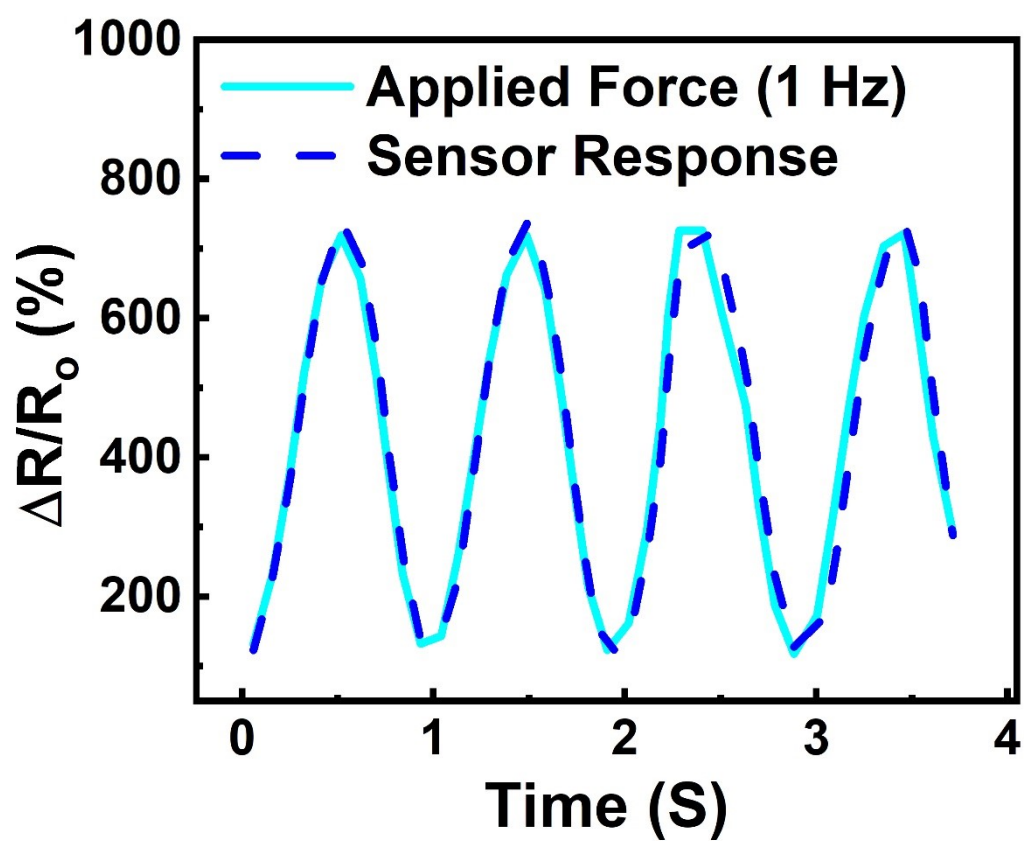


Fig. S8 Sensor response under uniaxial stretching at the rate of 1 Hz.

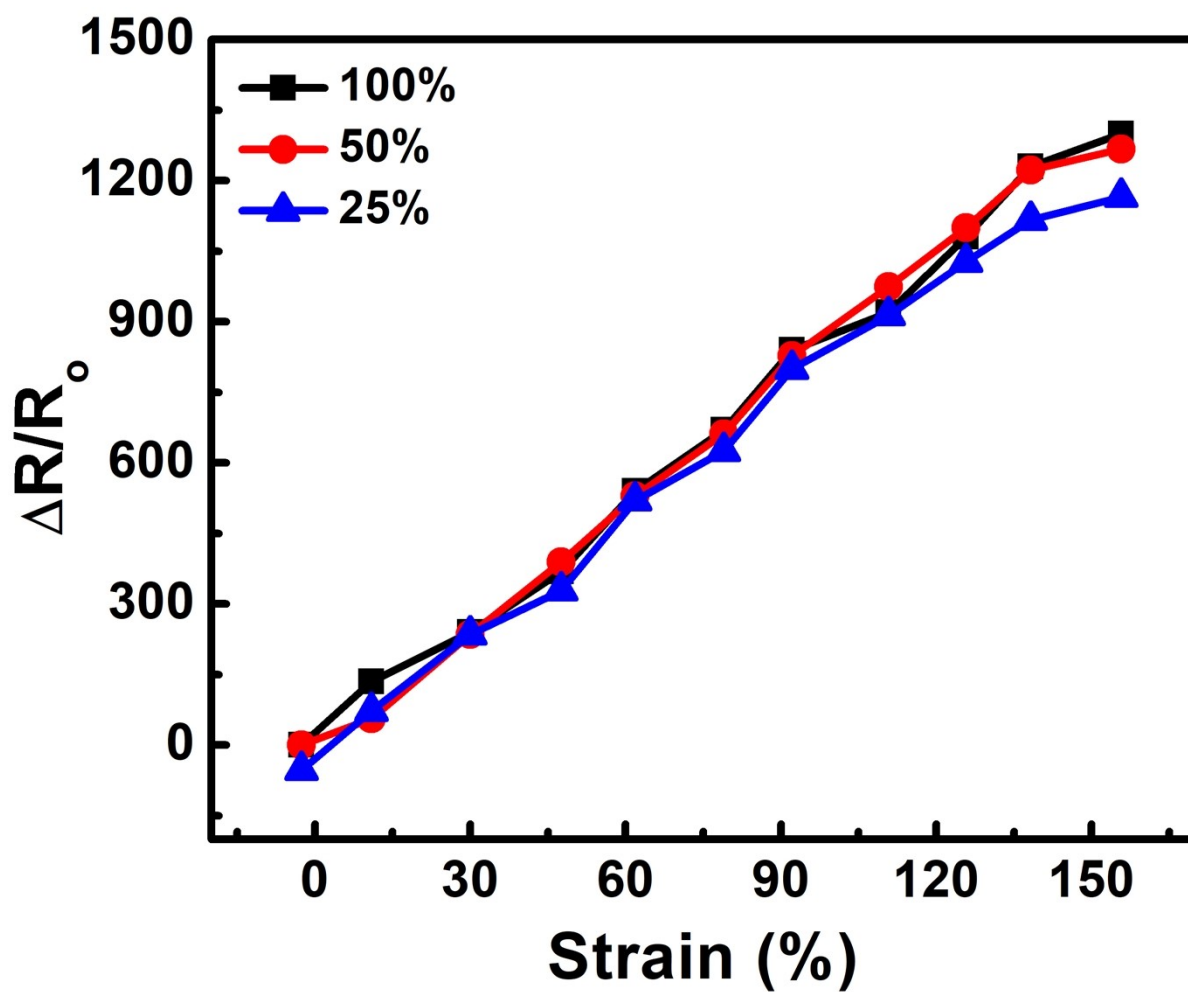


Fig. S9 Sensor's response when the LED is placed at different focus areas (25%, 50%, and 100%)

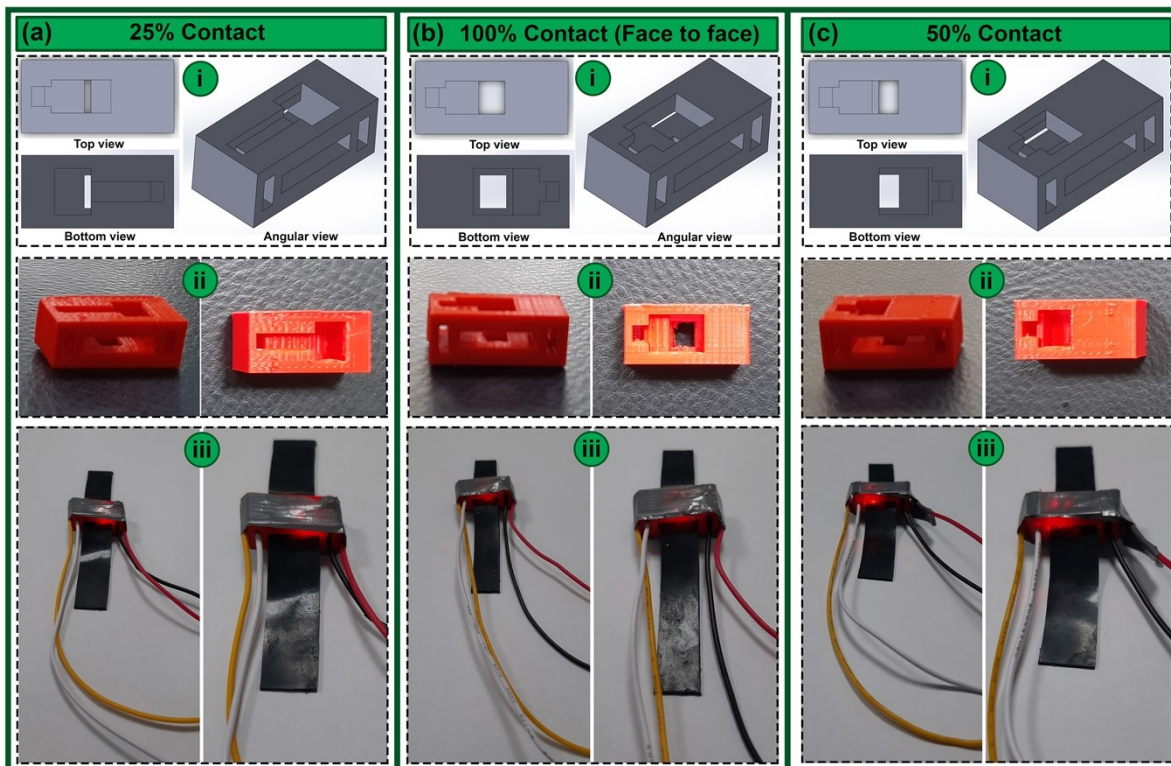


Fig. S10 (a) Shows the 3D drawing of the case with 25% focus area covered and its setup, (b) with 100% focus area, and (c) 50% focus area.

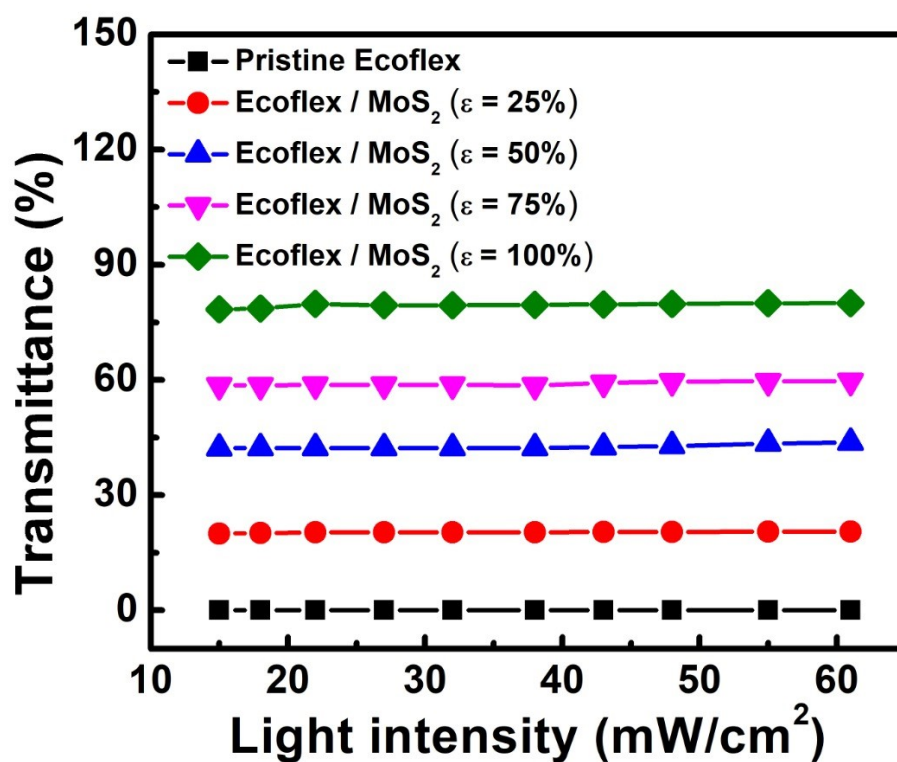


Fig. S11 Optical transmittance of the pristine Ecoflex and Ecoflex/MoS₂ when light intensity in the range of 12.5 – 52 mW/cm² was used.

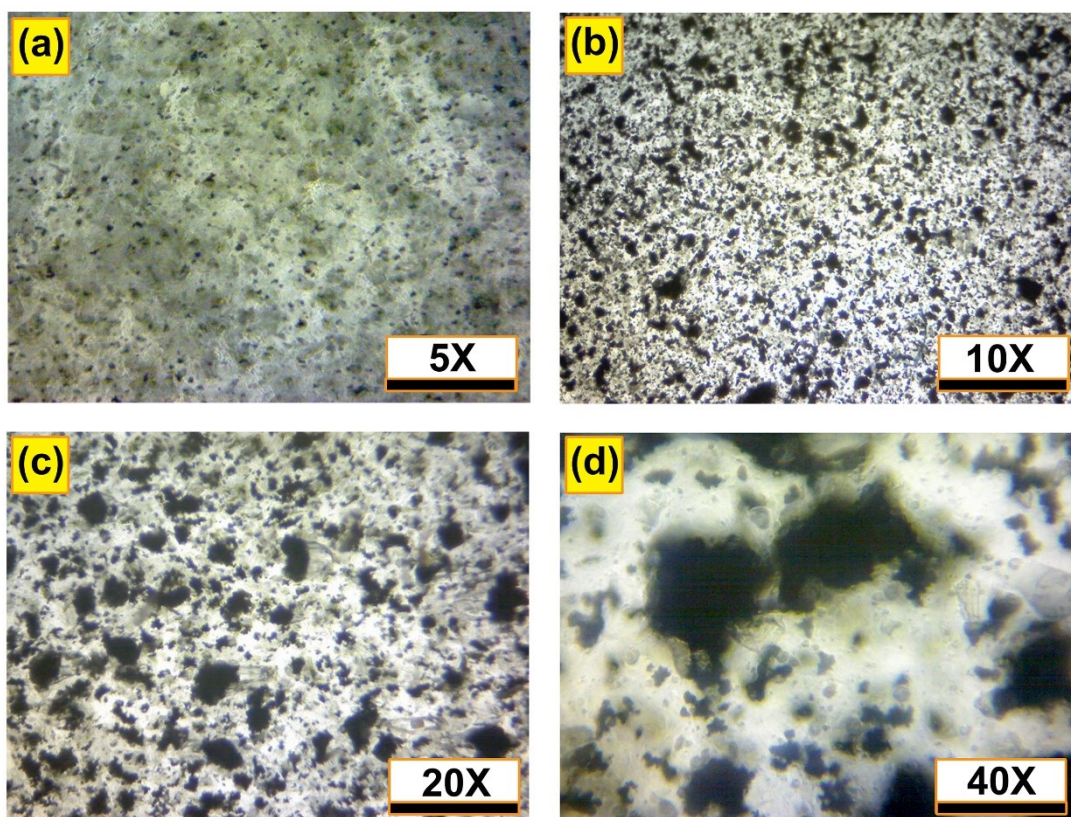


Fig. S12 microscopic images of the prepared membrane under different magnification levels (5X, 10X, 20X, and 40X).

Table S1 Comparison of performance parameters of the proposed device with reported devices

| Sensing Material | Matrix Material | Sensing Range | Strain Frequency | DH (%) | GF | Cycles | COD | Technique | Ref. |
|-------------------------------|-----------------|---------------|------------------|--------|--------|--------|---------------|--------------|---------------|
| GO-doped PU@PEDOT c | PU | 550% | -- | -- | 10.1 | 10000 | -- | Piezo Type | ¹ |
| GaInSn | PDMS | 50% | -- | -- | -- | 20 | Almost linear | Liquid type | ² |
| CNT | PDMS | 300% | -- | -- | 6.6 | 10000 | 0.9999 | Piezo Type | ³ |
| NaCl-Ecoflex | Ecoflex | 50% | -- | 21.34% | -- | -- | ~0.999 | Liquid type | ⁴ |
| Carbon grease solution | Ecoflex | 100% | -- | 9.04% | 3.8 | 1000 | Non-linear | Liquid type | ⁵ |
| multi-walled CNTs | PDMS | 60% | -- | -- | 1.16 | 255 | Non-linear | Piezo Type | ⁶ |
| KI-Gly | Ecoflex | 50% | 2 Hz | 5.3% | 2.2 | 4000 | Almost linear | Liquid type | ⁷ |
| Ethylene glycol/NaCl | Ecoflex | 250% | -- | 6.52% | <4 | 3000 | ~0.989 | Liquid type | ⁸ |
| PEDOT: PSS | PDMS | 30% | -- | ~9% | 12,000 | -- | -- | Liquid type | ⁹ |
| Graphene/ Glycerine | Ecoflex | 1000% | -- | -- | 45 | 10,000 | Almost linear | Liquid type | ¹⁰ |
| CNTs | Ecoflex | 100% | -- | 1.8% | 30 | -- | 0.98 | Piezo Type | ¹¹ |
| rGO/DI | Ecoflex | 400% | -- | 31.6% | -- | -- | Almost linear | Liquid type | ¹² |
| KCL-Gly | Ecoflex | 100% | 5 Hz | 4.23% | 2.7 | 8000 | ~0.99 | Piezo Type | ¹³ |
| PEDOT:PSS/M WCNT | Ecoflex | 150% | 10 Hz | 1.56% | 89.4 | 1000 | 0.99 | Liquid type | ¹⁴ |
| MOS₂ | Ecoflex | 150% | 5 Hz | 0.43% | 8.6 | 1000 | 0.998 | Optical Type | This work |

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