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1 Supplementary figure



Fig. S1 Wavelength variation trend of pedal waves along radial coordinate r while collecting varyingsized particles.



Fig. S2 (A) Pencil of $\xi \cdot d$ curves and orthogonal trajectories. (B)-(C) Relationship between d and φ in varying slopes k of orthogonal trajectories.



Fig. S3 Probability of particle collection satisfies the exponential distribution. The probability P(d) is set to 1% at $\overline{d} = 1.0$, which means an imaginarily large particle located in a diameter equivalent to the funnel radius cannot to collect by the snail.



Fig. S4 (A) Natural feeding behavior of a water snail that uses its foot to collect particles floating on the water surface. (B)-(C) SEM images of the snail foot surface. The cilia are densely distributed on textured surface of snail foot. (D) Samples for preparing foot muscle slices. (E)-(F) Distribution of foot muscles of the snail. Thin longitudinal section of the muscle stained with masson dye solution, showing transverse muscles (TM), oblique muscles (OM) , longitudinal muscles and connective tissue (CT) surrounding the muscles.



Fig. S5 Transport time and energy consumption when transporting different particles by varying

amplitudes. The dotted line is used to compare the transport time and energy consumption at a specific amplitude, in which the colored lines indicate that varying amplitudes are used to transport different particles and the black line indicate that a specific amplitude is used to transport.

2 Supplemental information

3 S1. Particle velocity

Considering a two-dimensional situation, in the frame fixed to the foot surface wave,
applying the lubrication approximation to the incompressible Navier-Stokes equation,
we have

$$\frac{\partial p}{\partial r} = \mu \frac{\partial^2 u_r}{\partial z^2}, \ \frac{\partial p}{\partial z} = 0,$$
 Equation S1

7 in which u_r is the component of velocity along the *r*-direction, and *p* is the pressure. 8 First, we rationalize the flow of mucus covering the foot surface. The boundary 9 conditions for Equation S1 can be expressed as $u_r = -V_w$ at z = f, as well as $\frac{\partial u_r}{\partial z} = 0$ 10 at z = h, where *f* and *h* are the vertical position of the foot surface and the gas-liquid 11 interface, respectively. Since *p* depends upon merely *r* rather than *z*, $\frac{\partial p}{\partial r}$ can be written 12 as $\frac{dp}{dr}$. Integrating Equation S1 in the *r*-direction twice with respect to *z*, while using 13 the boundary conditions, we arrive at the velocity of the mucus flow as

$$u_r = -V_w - \frac{1 \ dp}{2\mu dr} [(h-f)^2 - (h-z)^2].$$
 Equation S2

14 Further, integrating the velocity with respect to z, we get the rate of volume flow at 15 each cross-section as

$$q = \int_{f}^{h} u_{r} dz = -V_{w}(h-f) + \frac{(h-f)^{3} dp}{3\mu \ dr'}$$
 Equation S3

which is a time-independent constant because the mucus thickness is time-invariant inthe wave frame.

18 When the free surface remains approximately flat and undisturbed, the mucus is 19 validated to be actuated by the pedal waves, rather than the hydrostatic pressure or 20 surface tension¹. In other words, the location of the free surface can be approximated

as a critical constant h_0 . We may derive a relationship of $h \neq h_0$, otherwise the pressure 21 would be uniform and there would be no flow on the no-slip surface. There might have 22 two ultimate states to the free surface location. For the first state where the capillary 23 number Ca tends to infinity, the interface shape exactly conforms to the wavy shape of 24 the foot. In the other state with $Ca \approx 0$, the mucus-air interface becomes flat². To get an 25 approximately flat free surface, the change in mucus thickness is required to satisfy 26 $|h - h_0| \ll f_0$. According to the momentum equations in the *r*-direction, viscous stresses 27 must be balanced by the pressure gradient. By balancing the terms and rearranging, an 28 29 approximately flat free surface is given by (3.9) of¹:

$$\frac{\rho g (h_0 - f_0)^2}{\sigma} \gg \frac{\lambda}{f_0} Ca, \ Ca \equiv \frac{\mu U}{\sigma} \ll \frac{(h_0 - f_0)^2 f_0}{\lambda^3}.$$
 Equation S4

We consider mucus has the same density and surface tension as water, while being 100 times in viscosity¹. By introducing the numbers of the mucus thickness H = 1 mm, the amplitude $f_0 = 0.1$ mm, and the wavelength $\lambda = 0.5$ mm, we can extend Equation S4 into $Ca \equiv 10^{-3} \ll 0.4$ that satisfies the flat free surface approximation. So, in the following derivations, h can be replaced by h_0 .

35 The rate of volume flow at each cross section in the laboratory frame is 36 $Q = q + v_w(h_0 - f)$, then the volume flow averaged by total duration at each cross section

can be calculated by integrating over the period:
$$Q^{mean} = \int_{0}^{T} Qdt / T = q + V_{w} h_{0}$$

38 Substituting Q^{mean} into Equation S3, and introducing the dimensionless amplitude 39 $\varphi = f_0/h_0$ and dimensionless volume flow $\theta = Q^{mean}/(V_w h_0)$, we get

37

$$\frac{h_0^2}{\mu V_w \lambda} dp = \frac{3\varphi \left(\theta - \frac{f}{f_0}\right)}{\lambda \left(\varphi \frac{f}{f_0} - 1\right)^3} dr.$$
 Equation S5

40 Actually, dimensionless amplitude φ is a small quantity. We rewrite right side of

41 Equation S5 by Taylor expansion, keeping it to the order of φ^3 :

$$\frac{h_0^2}{\mu V_w \lambda} dp = \frac{1}{\lambda} \left[3\varphi \left(\frac{f}{f_0} - \theta \right) + 9\varphi^2 \frac{f}{f_0} \left(\frac{f}{f_0} - \theta \right) + 18\varphi^3 \left(\frac{f}{f_0} \right)^2 \left(\frac{f}{f_0} - \theta \right) \right] dr, \quad \text{Equation S6}$$

42 Integrating both sides of the equation simultaneously, we get

$$\frac{h_0^2}{\mu V_w \lambda} \Delta p_\lambda = -3\theta \varphi + \frac{9}{2} \varphi^2 - 9\theta \varphi^3,$$
 Equation S7

43 where Δp_{λ} is the pressure rise within one wavelength. Considering the case of $\Delta p_{\lambda} = 0$, 44 Equation S7 can be transformed into

$$\theta = \frac{3\varphi}{2(3\varphi^2 + 1)}.$$
 Equation S8

45 Next, we rationalize the flow of mucus around the particle. We consider that an 46 oblate cylindrical floating particle moves radially along the foot without direct contact with the foot. Assuming that the particle is moving with velocity V_s , the boundary 47 conditions for Equation S1 can be expressed as $u_r = -V_w$ at z = f, as well as 48 $u_r = V_s - V_w$ at $z = h_s$, in which h_s is the position of the lower surface of the particle. Since 49 we consider the shape of the particle as an oblate cylinder, the lower surface of the 50 particle is flat and h_s keeps constant in the static equilibrium. Consistent with the 51 derivation of the flow of mucus covering the foot surface, we arrive at the velocity of 52 the local flow in the area between the lower surface of the particle and the surface of 53 54 the foot as

$$u_r = -V_w + \frac{z - f}{h_s - f}V_s + \frac{1}{2\mu dr}(z - h_s)(z - f).$$
 Equation S9

55 Further, the rate of volume flow at each cross-section can be expressed as

$$q_{s} = -V_{w}(h_{s} - f) + V_{s}h_{s} - \frac{(h_{s} - f)^{3}dp}{12\mu \ dr},$$
 Equation S10

56 which can be averaged by total duration in the laboratory frame is $Q_{s}^{mean} = q_{s} + V_{w}h_{s}$. 57 Substituting Q_{s}^{mean} into Equation S10, then introducing the dimensionless amplitude 58 $\varphi_s = f_0/h_s$ and dimensionless volume flow $\theta_s = Q_s^{mean}/(V_w h_s)$ and dimensionless velocity 59 $\chi = V_s/V_w$ into Equation S10, we get

$$\frac{h_s^2}{\mu V_w \lambda} dp = \frac{12 \left(\theta_s - \varphi_s \frac{f}{f_0}\right) + 6 \left(\varphi_s \frac{f}{f_0} - 1\right) \chi}{\lambda \left(\varphi_s \frac{f}{f_0} - 1\right)^3} dr, \qquad \text{Equation S11}$$

60 We rewrite right side of Equation S11 by Taylor expansion, keeping it to the order of 61 $\varphi_{s:}^{3}$

$$\frac{h_s^2}{\mu V_w \lambda} dp$$

$$= \frac{1}{\lambda} \left[6\chi + 12\varphi_s \left(\frac{f}{f_0} \chi + \frac{f}{f_0} - \theta_s \right) \right]$$
Equation S12
$$dr,$$

62 Integrating both sides of the equation, we get

$$\frac{h_s^2}{\mu V_w \lambda} \Delta p_\lambda = 6\chi - 12\theta_s \varphi_s + (9\chi + 18)\varphi_s^2 - 36\theta_s \varphi_s^3,$$
 Equation S13

63 Considering the case of $\Delta p_{\lambda} = 0$, Equation S13 can be transformed into

$$\theta_s = \frac{6\varphi_s^2 + (3\varphi_s^2 + 2)\chi}{4\varphi_s(3\varphi_s^2 + 1)}.$$
 Equation S14

In order to match the particle local flow with the global flow, we apply the results above to the axisymmetric configuration of the biological funnel. Extending from twodimensional case to three-dimensional one, the width-integrated flux of whole foot flow $\Phi = 2\pi r Q^{mean}$ may be equal to the width-integrated flux of particle local flow $\Phi_s = dQ^{mean}_{s}$. Due to the flow loss of mucus passing through particles in tangential directions, the matching of the two flows should be written as $\Phi_s = (1-K) \Phi$ where K is a leakiness coefficient K to measure the volume flow loss of mucus between the pedal wave and the lower surface of the particle in other non-radial directions. 72 Expressing the matching of the flow as $2\pi r (1-K) \theta = d\theta_s$ in dimensionless numbers 73 and substituting Equation S8 and Equation S14 into it, we rearrange it to get

$$\chi = \frac{12\varphi^2 \pi (3\varphi^2 + \xi^2)}{(3\varphi^2 + 1)(3\varphi^2 + 2\xi^2)\xi d} (1 - K) r - \frac{6\varphi^2}{3\varphi^2 + 2\xi^2}.$$
 Equation S15

74 where $\xi = \varphi/\varphi_s = h_s/h_0$ is a dimensionless number characterizing the relative magnitudes 75 of h_s and h_0 . We introduce two dimensionless numbers $\bar{r} = r/r_0$ and $\bar{d} = d/r_0$, which 76 characterize the position of the particle on the surface of the foot and the relative size 77 of the particle and the funnel, respectively, to make all the variables in Equation S15 78 dimensionless. In a dimensionless frame, the relationship between the velocity and the 79 radial position on the foot surface of the particle can be expressed as

$$\chi = \frac{12\varphi^2 \pi (3\varphi^2 + \xi^2)}{(3\varphi^2 + 1)(3\varphi^2 + 2\xi^2)\xi \bar{d}} (1 - K) \bar{r} - \frac{6\varphi^2}{3\varphi^2 + 2\xi^2}.$$
 Equation S16

80 S2. The supporting force for mucus

To calculate the supporting force provided by the mucus to the particles, we rewriteEquation S12 as follows

$$\frac{h_0^2}{\mu V_w \lambda} dp$$

$$= \frac{1}{\lambda \eta^2} \left[6\chi + 12 \frac{\varphi}{\xi} \left(\frac{f}{f_0} \chi + \frac{f}{f_0} - \frac{f}{\zeta} \right) \right]$$
Equation S17
$$dr.$$

Substituting Equation S16 into Equation S17 and integrating both sides simultaneously, we can get the pressure p. To eliminate the effect of time, we calculate the timeaveraged pressure distribution of the water film under the particle according to

 $p^{mean} = \int_{0}^{T} p dt / T$ and arrive at dimensionless time-averaged pressure as

$$\frac{h_0^2}{\mu V_w \lambda} p^{mean} = \frac{18\pi K \varphi^2 (3\varphi^2 + \xi^2)}{\eta^5 (3\varphi^2 + 1) d\lambda} \left(r_0^2 - r^2\right), \quad \text{Equation S18}$$

87 in which we confirmed that the constant term due to the integration by setting the 88 boundary condition $p^{mean}|_{r=r_0} = 0$ and r_0 is the position of the snail foot edge. For 89 simplification, in the following text, we rewrite p^{mean} as p. Using \bar{r} and \bar{d} to make all 90 the variables in Equation S18 dimensionless, the dimensionless pressure acting on the 91 lower surface of the particle along the radial direction of the foot can be expressed as

$$\frac{h_0^2}{\mu V_w r_0} p = \frac{18\pi K \varphi^2 (3\varphi^2 + \xi^2)}{\xi^5 (3\varphi^2 + 1)\bar{d}} (1 - \bar{r}^2).$$
 Equation S19

92 S3. Numerical solution of eqn (5)

The numerical results show that all $\xi \overline{d}$ curves exhibit inverse proportional principles with varying φ . Examining the slope variation of each curve along the coordinate \overline{d} , we notice that the orthogonal trajectories of $\xi \overline{d}$ curve family are the lines through the origin (Fig. S2A). We intend to record the intersections of the curves with orthogonal trajectories in varying slopes k and express the relationship between \overline{d} and φ at these points with an approximate equation.

99 First, we assume that \vec{d} is proportional to the power of φ , which can be expressed as $\vec{d} = A\varphi^B$. Equation S20

Fitting \vec{a} with Equation S20 in varying k and comparing the fitting results (Tab. S1), we notice that the parameter A is sensitive to k, while B is not. Therefore, we keep the parameter B constant at B = 0.4 and rewrite Equation S20 as

$$\bar{d} = A\varphi^{0.4}$$
. Equation S21

103 According to results of Equation S21 fitting (Fig. S2B), we consider A to be a function 104 of k . To understand the varying in slopes of the orthogonal trajectories, we fit $^{A(k)}$ in a 105 form of a power function (Fig. S2C), written as

$$A(k) = mk^n$$
. Equation S22

106 Substitute the fitting result into Equation S21, the relationship between \overline{d} and φ can be 107 expressed as

 $\bar{d} = 0.67k^{0.58} \cdot \varphi^{0.4}$. Equation S23

k	0.5	1	2	5	10
A	0.174	0.263	0.451	0.675	1.007
$\Delta A/\Delta k$	/	17.8%	18.5%	11.1%	8.8%
В	0.397	0.396	0.394	0.391	0.388
$\Delta B / \Delta k$	/	0.2%	0.2%	0.1%	0.1%
R^2	0.99999	0.99999	0.99998	0.99996	0.99995

Tab. S1 Results of Equation S20 fitting

108 S4. Transport time and mass intake rate

109 Since $\chi = -d\bar{r}/d\bar{t}$ where duration time *t* is dimensionless to $\bar{t} = t \cdot V_w/r_0$ and the 110 negative sign indicates that the particle is moving from the edge of the foot to the center 111 of the foot, we rewrite Equation S16 as

$$-\frac{d\bar{r}}{d\bar{t}} = C_1\bar{r} + C_2, \quad \text{Equation S24}$$

112 where parameters C_1 and C_2 can be expressed as

$$C_{1} = \frac{12\phi^{2}\pi(3\phi^{2} + \xi^{2})}{(3\phi^{2} + 1)(3\phi^{2} + 2\xi^{2})\xi\bar{d}} (1 - K) ,$$

$$C_{2} = -\frac{6\phi^{2}}{3\phi^{2} + 2\xi^{2}}.$$

Equation S25

113 We consider that the moment when the particles are transported inward from the edge

114 of the pedal wave is $\bar{t} = 0$, namely the initial condition of Equation S24 is $\bar{r}|_{\bar{t}} = 0 = 1$

115 Solving the equation with this initial condition, we arrive at the explicit relationship 116 between \bar{r} and \bar{t} as

$$\bar{r} = -\frac{C_2}{C_1} + e^{-C_1\bar{t}} \left(1 + \frac{C_2}{C_1}\right).$$
 Equation S26

117 Assuming that the particle is transported to the position $\bar{r} = \bar{r}_t$ and just leave the flat 118 portion of the funnel at $\bar{t} = \bar{T}_t$, we can rearrange Equation S26 as

$$\bar{T}_t = -\frac{1}{C_1} \ln \left(\frac{\bar{r}_t + \frac{C_2}{C_1}}{1 + \frac{C_2}{C_1}} \right), \quad \text{Equation S27}$$

119 where T_t is the dimensionless form of the particle transport time T_t .

120 S5. Energy cost of changing waveforms

To quantify energy cost during the snail altering the waveform, we model the snail foot composed of a linear elastic material. For steady waves, in the case of small deformation, the dimensionless power that the snail output to maintain the forced vibration of the foot muscles can be expressed as

$$\varepsilon \sim \frac{32\pi^2 H^2}{16^2 + D^2}$$
, Equation S28

125 in which H and D are dimensionless parameters identifying the characteristic strength 126 of forced vibration and the stiffness of the foot muscles, respectively³. According to 127 previous models that specify the wall displacement in a sinusoidal form⁴⁻⁶, we have the 128 connections between ϕ and D as

$$\varphi \frac{f}{f_0} \sim D \frac{16\cos\left(\frac{2\pi}{\lambda}r\right) + D\sin\left(\frac{2\pi}{\lambda}r\right)}{16^2 + D^2}.$$
 Equation S29

129 Integrating both sides of the equation simultaneously, we get $\varphi \sim D$. Therefore, the 130 dimensionless power can be expressed as

$$\varepsilon \sim \varphi^2$$
. Equation S30

Further, we can calculate the energy consumption of the snail during a transport by $E = \varepsilon \cdot \overline{T}_t$ where \overline{E} is the dimensionless energy consumption. We compared the changes in dimensionless transport time and dimensionless energy consumption when transporting the particles in different sizes by different amplitudes (Fig. S5). As the amplitude increases, the transport time for a single particle will decrease, but the energy 136 consumption will increase, which requires the snail to balance time cost and energy 137 cost. Taking $\overline{d} = 0.05$ as an example, compared with $\varphi = 0.03$, using the amplitude in 138 $\varphi = 0.0375$ can only help the snail save 15.4% of the energy but the snail has to spend 139 29.3% more time to transport the particle.

140 **References**

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